



The grid world environment is a 10x10 grid. The robot is located at (1, 1). The goal is located at (9, 9). Obstacles are located at (3, 3), (4, 4), (5, 5), (6, 6), (7, 6), and (8, 6). Rewards are located at (2, 2), (5, 3), (6, 3), and (7, 3).